

Subdivision Schemes for Geometric Modelling

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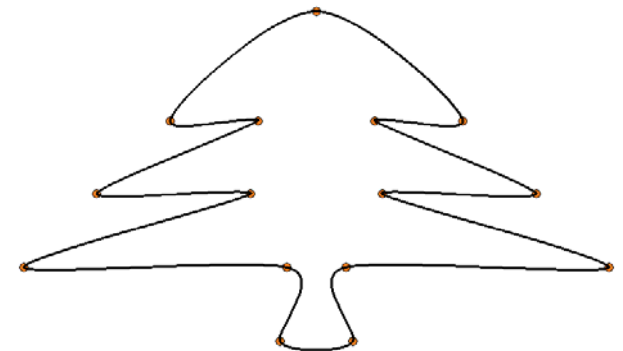
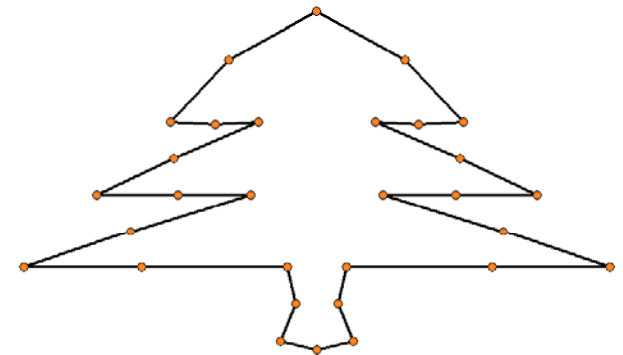
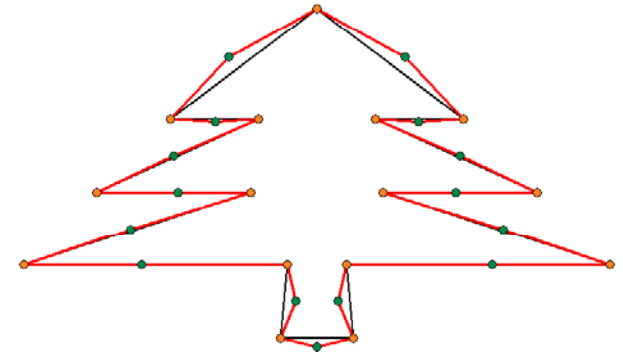
What it is all about

“Subdivision defines a smooth curve or surface as the limit of a sequence of successive refinements.”

Denis Zorin & Peter Schröder
SIGGRAPH 98 course notes

Subdivision curves

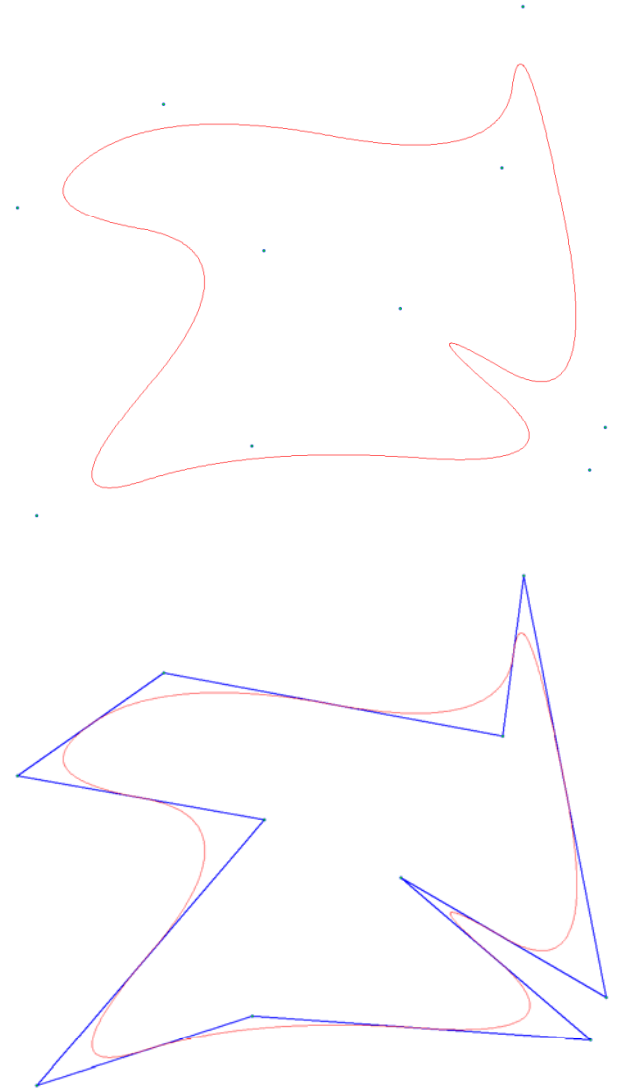
- initial control polygon
 - rough, user-sketched shape
- iterative refinement
 - adding new points
 - simple local rules
- smooth limit curve
 - finitely many steps in practice
 - up to pixel accuracy



- subdivision curves in computer-aided design
 - modify initial control points
 - alternative to splines

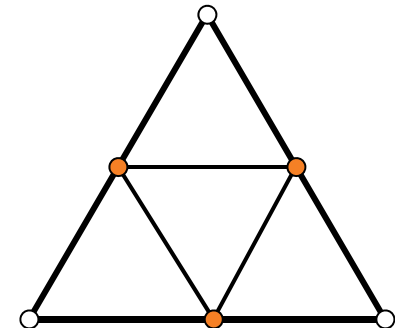
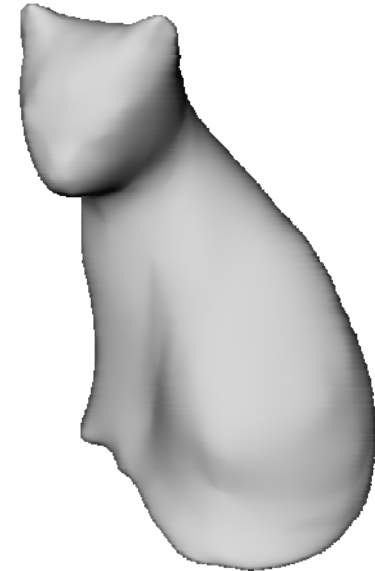
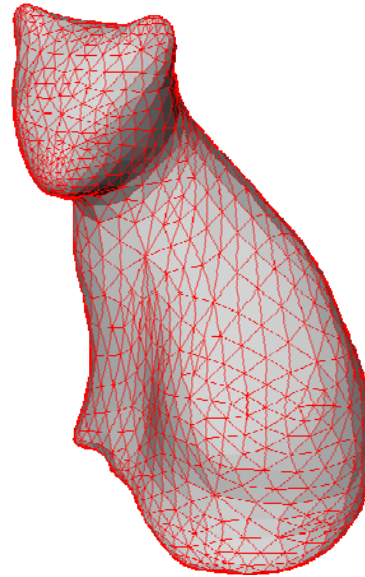
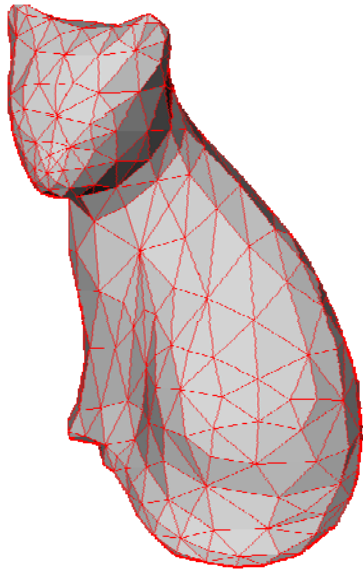


- simple and efficient curve representation



Subdivision surfaces

- iterative, regular refinement
 - simple local rules
 - efficient



- subdivision surfaces in computer graphics

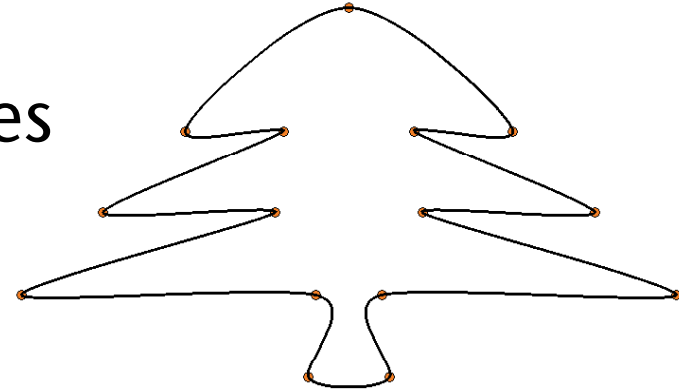


- simple and efficient surface representation



Subdivision curves and surfaces

- vast playground
 - abundance of rules and schemes
- standard goals
 - convergence
 - smoothness
- standard limitations
 - artefacts at extraordinary vertices
- new trend
 - nonlinear, geometric methods



Subdivision curves and surfaces

- important properties
 - convergence
 - existence of limit curve/surface
 - smoothness of the limit curve/surface
 - affine invariance
 - simple local rules
 - efficient evaluation
 - compact support of basis function
 - polynomial reproduction
 - approximation order

- *Sep 5 – Subdivision as a linear process*
 - *basic concepts, notation, subdivision matrix*
- Sep 6 – The Laurent polynomial formalism
 - algebraic approach, polynomial reproduction
- Sep 7 – Smoothness analysis
 - Hölder regularity of limit by spectral radius method
- Sep 8 – Subdivision surfaces
 - overview of most important schemes & properties

Basic concept and notation

- initial *control polygon*
 - sequence of *control points* $\{p_i^0\}$ (2D/3D) at *level 0*
 - open ($i \in \{i_{min}, \dots, i_{max}\}$) or closed ($i \in \mathbb{Z}$)
- *refinement rules*
 - how to get from level j to level $j+1$
 - simplest case (*interpolatory* subdivision)

$$p_{2i}^{j+1} = p_i^j, \quad p_{2i+1}^{j+1} = \sum_k \beta_k p_{i-k}^j$$

- reproduce *old points* and insert *new points*

A simple interpolatory scheme

■ Example

$$p_{2i}^{j+1} = p_i^j, \quad p_{2i+1}^{j+1} = \overset{\beta_0}{\downarrow} \frac{1}{2} p_i^j + \overset{\beta_{-1}}{\downarrow} \frac{1}{2} p_{i+1}^j$$

- new points at old edge midpoints
- shape of control polygon does not change
- points become denser with increasing level j
- control polygon is also the *limit curve*
- refinement rules depend on 2 old points at most, hence this is called a *2-point scheme*

A non-interpolatory scheme

■ Example

$$p_{2i}^{j+1} = \frac{1}{8} p_{i-1}^j + \frac{6}{8} p_i^j + \frac{1}{8} p_{i+1}^j, \quad p_{2i+1}^{j+1} = \frac{1}{2} p_i^j + \frac{1}{2} p_{i+1}^j$$

- *approximating* scheme (old points are modified)
- 3-point scheme
- gives uniform cubic B-splines in the limit
- convenient notation for refinement rules
 - *even stencil* $[1, 6, 1]/8$ *odd stencil* $[1, 1]/2$
 - index offsets clear by symmetry

The subdivision matrix

- write refinement rules, one below the other,

$$\begin{pmatrix} \vdots \\ p_{2i-2}^{j+1} \\ p_{2i-1}^{j+1} \\ p_{2i}^{j+1} \\ p_{2i+1}^{j+1} \\ p_{2i+2}^{j+1} \\ \vdots \end{pmatrix} = \begin{pmatrix} \dots & & & & & & \\ & \frac{1}{8} & \frac{6}{8} & \frac{1}{8} & & & \\ & & \frac{1}{2} & \frac{1}{2} & & & \\ & & \frac{1}{8} & \frac{6}{8} & \frac{1}{8} & & \\ & & & \frac{1}{2} & \frac{1}{2} & & \\ & & & \frac{1}{8} & \frac{6}{8} & \frac{1}{8} & \\ & & & & & & \dots \end{pmatrix} \cdot \begin{pmatrix} \vdots \\ p_{i-2}^j \\ p_{i-1}^j \\ p_i^j \\ p_{i+1}^j \\ p_{i+2}^j \\ \vdots \end{pmatrix}$$

- gives the *subdivision matrix* S
 - with stencils as rows (alternating and shifted)

Subdivision in the limit

- refinement from level j to level $j+1$

$$\mathbf{p}^{j+1} = S\mathbf{p}^j$$

- refinement from level 0 to level j

$$\mathbf{p}^j = S\mathbf{p}^{j-1} = S^2\mathbf{p}^{j-2} = \dots = S^j\mathbf{p}^0$$

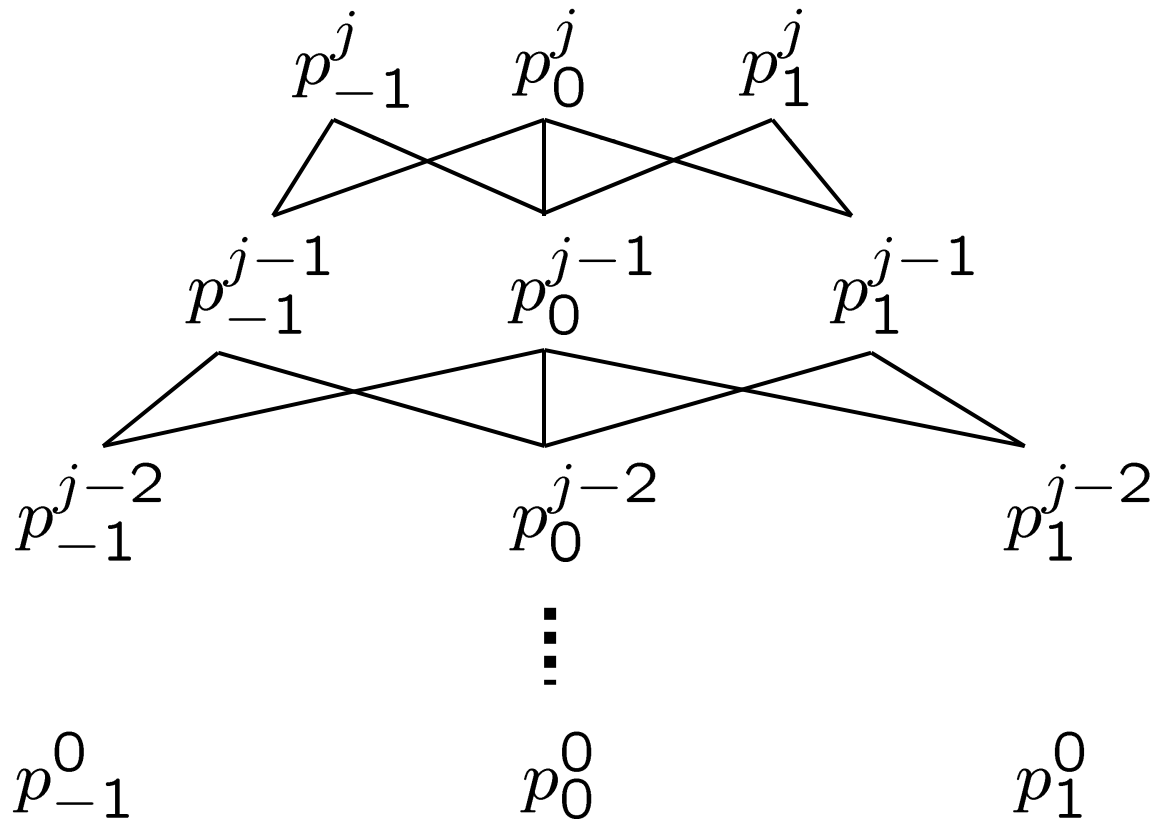
- refinement in the limit

$$\mathbf{p}^\infty = \lim_{j \rightarrow \infty} \mathbf{p}^j = \lim_{j \rightarrow \infty} S^j\mathbf{p}^0 = S^\infty\mathbf{p}^0$$

- but S is an infinite matrix, so what is S^∞ ?

Subdivision in the limit

- local analysis with *invariant neighbourhood*
 - which initial control points determine p_0^j ?



Subdivision in the limit

- local analysis for p_0^j in the limit (as $j \rightarrow \infty$)

$$\begin{pmatrix} p_{-1}^j \\ p_0^j \\ p_1^j \end{pmatrix} = \underbrace{\begin{pmatrix} \frac{1}{2} & \frac{1}{2} & 0 \\ \frac{1}{8} & \frac{6}{8} & \frac{1}{8} \\ 0 & \frac{1}{2} & \frac{1}{2} \end{pmatrix}}_{=S} \cdot \begin{pmatrix} p_{-1}^{j-1} \\ p_0^{j-1} \\ p_1^{j-1} \end{pmatrix}$$

- compute eigendecomposition of S

$$S = Q \cdot \Lambda \cdot Q^{-1}, \quad Q = \begin{pmatrix} 1 & -1 & -2 \\ 1 & 0 & 1 \\ 1 & 1 & -2 \end{pmatrix}, \quad \Lambda = \begin{pmatrix} 1 & & \\ & 1/2 & \\ & & 1/4 \end{pmatrix}$$

- and so $S^j = (Q \cdot \Lambda \cdot Q^{-1})^j = Q \cdot \Lambda^j \cdot Q^{-1}$

- now letting $j \rightarrow \infty$

$$S^\infty = \lim_{j \rightarrow \infty} S^j = \lim_{j \rightarrow \infty} Q \cdot \Lambda^j \cdot Q^{-1} = Q \left(\lim_{j \rightarrow \infty} \Lambda^j \right) Q^{-1}$$

$$\begin{aligned} \begin{pmatrix} p_{-1}^\infty \\ p_0^\infty \\ p_1^\infty \end{pmatrix} &= \begin{pmatrix} 1 & -1 & -2 \\ 1 & 0 & 1 \\ 1 & 1 & -2 \end{pmatrix} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} \frac{1}{6} & \frac{4}{6} & \frac{1}{6} \\ -\frac{1}{2} & 0 & \frac{1}{2} \\ -\frac{1}{6} & \frac{1}{3} & -\frac{1}{6} \end{pmatrix} \begin{pmatrix} p_{-1}^0 \\ p_0^0 \\ p_1^0 \end{pmatrix} \\ &= \begin{pmatrix} \frac{1}{6} & \frac{4}{6} & \frac{1}{6} \\ \frac{1}{6} & \frac{4}{6} & \frac{1}{6} \\ \frac{1}{6} & \frac{4}{6} & \frac{1}{6} \end{pmatrix} \begin{pmatrix} p_{-1}^0 \\ p_0^0 \\ p_1^0 \end{pmatrix} \end{aligned}$$

- observations
 - convergence requires that 1 is an eigenvalue of S and that all other eigenvalues are smaller
 - first row of Q^{-1} gives the *limit stencil* $[1, 4, 1]/6$
 - applying it to three consecutive control points gives the limit position of the central one
 - works on any level
 - can be used to “snap” the points to the limit curve
 - can be used to estimate distance to the limit curve

■ Example

$$p_{2i}^{j+1} = p_i^j$$

$$p_{2i+1}^{j+1} = \frac{1}{16}(-p_{i-1}^j + 9p_i^j + 9p_{i+1}^j - p_{i+2}^j)$$

- classical *interpolatory 4-point scheme* [Dubuc 1986]
- based on local cubic interpolation
- even stencil [1] odd stencil $[-1, 9, 9, -1]/16$
- invariant neighbourhood size: 5
- eigenvalues of S : $1, 1/2, 1/4, 1/4, 1/8$
- limit stencil [1] (true for all interpolatory schemes)

The general 3-point scheme

■ Example

$$p_{2i}^{j+1} = \alpha_1 p_{i-1}^j + \alpha_0 p_i^j + \alpha_{-1} p_{i+1}^j$$

$$p_{2i+1}^{j+1} = \beta_0 p_i^j + \beta_{-1} p_{i+1}^j$$

- constraints: symmetry and summation to 1
 - even stencil $[w, 1-2w, w]$ odd stencil $[1, 1]/2$
- invariant neighbourhood size: 3
- eigenvalues of S : $1, 1/2, 1/2-2w$
- certainly not convergent for $w \notin (-1/4, 3/4)$
- limit stencil $[2w, 1, 2w]/(1+4w)$

- local limit analysis
 - determine size n of invariant neighbourhood
 - consider local $n \times n$ subdivision matrix S
 - **necessary condition** for convergence
 - 1 is the unique largest eigenvalue of S**
 - if coefficients of even/odd stencil sum to 1, then
 - 1 is an eigenvalue of S with eigenvector $(1, \dots, 1)$
 - subdivision scheme is affine invariant
 - limit stencil given by normalized **left eigenvector** of S with eigenvalue 1 (usual (right) eigenvector of S^T)